

STENT HAVING HELICAL ELEMENTS

This application claims the benefit of U.S. Provisional Application No. 60/254,688, filed on December 11, 2000, which is hereby incorporated in its entirety by reference, and it is a continuation-in-part of U.S. Pat App. Ser. No. 09/511,481, filed on Feb. 23, 2000, which is also hereby incorporated in its entirety by reference and which is a divisional of U.S. Pat. App. Ser. No. 09/094,402, filed June 10, 1998 (now U.S. Patent No. 6,117,165) that claims the benefit under 35 U.S.C. §119 of European Applications Ser. Nos. EPO 98201799.0, filed June 13, 1997 and EPO 98201446.6, filed May 6, 1998.

BACKGROUND OF THE INVENTION

1. Field of the Invention

The present invention relates to prosthetic stents. In particular, the present invention relates to stents having helical elements and to methods for manufacturing the stents of the present invention.

2. Description of Related Art

Stents are prosthetic devices that are implanted in the lumen of a vessel inside the body to provide support for the vessel's wall. Structural support from stents is particularly important in angioplasty procedures. Typically, stents are implanted within a vessel system to reinforce vessels that are partially occluded, collapsing, weakened, or abnormally dilated. More generally, stents can be used inside any physiological conduit or duct including, for example, arteries, veins, bile ducts, the urinary tract, alimentary tracts, the tracheobronchial tree, a cerebral aqueduct or the genitourinary system. Stents may be used in both humans and animals.

There are typically two types of stents: self expanding stents and balloon expandable stents. Self expanding stents automatically expand once they are released and assume a deployed, expanded state. A balloon expandable stent is expanded using an inflatable balloon catheter. The balloon is inflated to plastically deform the stent. Balloon expandable stents may be implanted by mounting the stent in an unexpanded or crimped state on a balloon segment of a catheter. The catheter, after having the crimped stent placed thereon, is inserted through a puncture in a vessel wall and moved through the vessel until it is positioned in the portion of the vessel that is in need of repair. The stent is then expanded by inflating the balloon catheter against the inside wall of the vessel. Specifically, the stent is plastically deformed by inflating the balloon so that the diameter of the stent is increased and remains at an increased state. In some situations, the vessel in which the stent is implanted may be dilated by the stent itself when the stent is expanded.

The Palmaz-Schatztm stent, which is disclosed in the Handbook of Coronary Stents by Patrick W. Serruys et al. (Martin Dunitz, LTD 1998), is an example of a balloon expandable

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stent that had been implanted in hundreds of thousands of patients. The Palmaz-Schatz[™] stent, like other known stents, has certain limitations. These include, but are not limited to: (i) low stent-to-vessel ratio uniformity, (ii) comparative rigidity of the stent in a crimped as well as deployed state, and (iii) limited flexibility making delivery and placement in narrow vessels difficult. Stent-to-vessel ratio generally refers to the degree that the vessel wall is supported by the stent in its expanded state and preferably should be uniform throughout the length of the stent. Furthermore because the Palmaz-Schatz[™] stent consists of one or more bridges that connect a number of consecutively slotted tubes, there are a number of bare areas in the vessel after the expansion of the stent. These shortfalls are common to many stents. Id. at 36.

SUMMARY OF THE INVENTION

The present invention is directed to an expandable stents that have relatively uniform stent-to-vessel ratios when expanded and other desirable properties, as well as methods for making these stents. The stents of the present invention comprise a generally cylindrically shaped main body having a plurality of expandable helical segments. The main body is comprised of a plurality of cylindrical main body elements that are joined together by the helical segments. The cylindrical elements have cylindrical axes that are collinear with the cylindrical axis of the main body. The cylindrical elements are formed from a plurality of circumferential elements that are joined together by the expandable helical segments. In some embodiments, the stent may comprise endzones that straddle the main body.

In one embodiment of the present invention, the stent may comprise a first non-helical endzone and a second non-helical endzone that straddle the main body. The main body is generally cylindrically shaped and has a cylindrical axis. A plurality of adjacent main body cylindrical elements are connected together to form the main body of the stent. Each main body cylindrical element may be comprised of a plurality of expandable first and second circumferential elements. In some embodiments, the second circumferential elements have a circumferential dimension less than the circumferential dimension of the first circumferential elements. In yet other embodiments, the first and second circumferential elements have the same circumferential dimensions and are substantially identical except that, with respect to the cylindrical axis of the stent, they are oriented differently. Each second circumferential segment in each main body cylindrical element is connected to two first circumferential segments. In addition, each second circumferential segment in each main body cylindrical element is connected to a second circumferential segment in an adjoining main body cylindrical element thereby forming a plurality of helices in the main body of the stent.

In one embodiment, the main body may be comprised of a plurality of first helical segments each having a substantially identical first pitch and a plurality of second helical

segments, each having a substantially identical second pitch. The first and second pitches are generally different. In at least one embodiment, the second pitch is twice that of the first, and at least one first helical segment crosses one of the second helical segments.

The stents of the present invention may be manufactured from a tubular member by removing material from the tube to form a first endzone region, a second endzone region, and a middle region. By removing material from the middle region a plurality of parallel helical segments will remain and a plurality of circumferential segments will remain connecting the helical segments. Alternatively, the stent may be formed from a tube by removing material such that at least two sets of helical segments remain with each set having a different pitch.

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is a three dimensional view of one embodiment of a stent according to the present invention in its unexpanded state.

Figure 2 is planar view of a flattened portion of the circumference of the stent in Figure 1.

Figure 3 is an enlarged portion of Figure 2.

Figure 4 is another planar view of a flattened portion of the circumference of a stent according to the present invention in its unexpanded state.

Figure 5 is an enlarged view of a portion of Figure 4 showing a first circumferential element of the stent.

Figure 6 is an enlarged view of a portion of Figure 4 showing a second circumferential element of the stent.

Figure 7 is a planar view of a flattened portion of the stent in Figure 1 showing a plurality of sets of helical segments propagating through the stent's body.

Figure 8 is a planar view of a flattened endzone that may be employed in a stent of the present invention.

Figure 9 is a planar view of a flattened portion of part of the endzone shown in Figure 8.

Figure 10 is a planar view of a flattened portion of an expandable stent according to the present invention, after the stent has been deployed in a lumen.

Figure 11 is three dimensional view of an alternative embodiment of the present invention.

Figure 12 is a three dimensional view of an another stent according to the present invention.

Figure 13 is a planar view of the stent shown in 12.

Figure 14 is a detailed view of a portion of Figure 13.

Figure 15 is a detailed view of another portion of Figure 13.

DETAILED DESCRIPTION OF THE INVENTION

The present invention is directed to an expandable stent, as well as a method of manufacturing the stent. In one embodiment, as is shown in Figures 1 and 2, the stent comprises a generally cylindrical shaped main body section **11** having a cylindrical axis **5** and a wall thickness **103**. The wall thickness **103** may optionally be uniform throughout the stent. The main body section **11** is comprised of a plurality of helical segments **30** and **40** and a plurality of main body cylindrical elements **100**, each having cylindrical axes (not shown) that are collinear with the main body cylindrical axis **5**. The main body cylindrical elements **100** are each comprised of circumferential elements **50** that are joined together by the helical segments **30** and **40** to form individual cylinders **100**.

The stent may also have a first endzone **10** and a second endzone **20** that straddle the body section **11**. In some embodiments, such as the one shown in Figure 1, the endzones **10** and **20** may advantageously provide the stent with square outer edges **8**. The stent may be manufactured from stainless steel, or other suitable materials. In most embodiments, it is desirable that the material, or a portion of the material, be radiopaque and that the various segments that form the stent be contiguous. Although, in some embodiments, the various segments that make up the stent can be distinct elements that are joined together.

The main body **11**, shown in Figures 1 and 2, may be formed in numerous ways. For example, the body **11** may contain two or more first helical segment **30** and **40** that are generally parallel to each other. In some embodiments they may be opposite each other by 180.°. In general, the first helical segments **30** and **40** will be spaced equidistant along the circumference **110** of the main body **11**. The first helical segments **30** and **40** are joined by a plurality of circumferential segments **50** to form a plurality of main body cylindrical elements **100**, which may be only generally cylindrically shaped. In one embodiment, the circumferential segments **50** make up a majority of the circumference **110** of each cylindrical element **100**. In addition to joining the circumferential elements **50** to form cylindrical elements **100**, the helical segments **30** and **40** connect each cylindrical element **100** to an adjacent cylindrical element **100** to form the main body **11**.

As is shown in Figure 3, the body of the stent **11** may comprise a plurality of main body cylindrical elements **100** formed from first circumferential segments **50** that are joined with second circumferential segments **60**. The second circumferential segments **60** of each cylindrical element **100** may be joined with second circumferential segments **60** of adjacent cylindrical elements **100** to form a plurality of first helical segments **30** and **40** in the main body **11**. (See Fig. 2). Each first circumferential segment **50** may have a circumferential dimension **55** and each second circumferential segments **60** may have a circumferential dimension **66**. (See Fig.3)

In some embodiments, it may be desirable for the circumferential dimension **55** of the first expandable element **50** to be larger than the circumferential dimension **66** of the second expandable element **60**.

The first circumferential segment **50** may be an expandable segment formed from plurality of segments joined together to form a pattern. The pattern, such as the one shown in the Figures 1-3, may be a repeating pattern that resembles a square wave form having curved peaks and valleys. Other patterns, both repeating and non-repeating, may be used. For example, and without limitation, the first circumferential segments **50** may resemble a triangle wave form, a sinusoidal wave form, other repetitious patterns, or any pattern that enables the segment to expand when a radial force is exerted on the stent from the inside or collapse radially when an external crimping force is applied.

The first circumferential elements **50** may have a filament width **420** (see Fig. 4). In one embodiment, the filament width may vary between 0.002 inches and 0.007 inches, but is preferably about 0.0050 inches. Other filament widths may be used depending on the parameters of the stent.

In the embodiment shown in Figs. 1-5, the first circumferential elements **50** comprise linear portions **320** and curved portions **328** that join the linear portions **320** together to form a repeating pattern. In some, but not all, embodiments, the linear portion **320** may be parallel to the cylindrical axis of the stent. The first circumferential segment **50** has an amplitude **350** and a period **380**. In one embodiment the amplitude may range from 0.5 mm to 2.0 mm and the period may range from 0.5 mm to 2.0 mm. In some embodiments, the amplitude is less than the period. Other amplitudes and periods may be used depending on the overall stent design and performance constraints.

The second circumferential element **60**, which may be joined together in a helical pattern to form one or more helical segments **30** or **40**, may also take numerous forms, in addition to the form shown in Figure 6. In the embodiment shown in Fig 6, the second circumferential element **60** comprises linear portions **412** and curved portions **414** having a filament width **407**, and resembles generally an S-shaped structure. In addition, the second element circumferential segment **60** may have an angled portion **417** attached to the linear portion **412** at an end opposite that of the curved portion **414**. The angled portion may be oriented to form an angle α relative to the cylindrical axis of the stent **5** in the range of 0-45 degrees. In at least one embodiment, the preferable angle α is about 10 degrees. In some embodiments, the linear portions **412** of the second circumferential element **60** lies at an angle Ω relative to the cylindrical axis of the stent, wherein Ω preferably ranges from 0 to 45 degrees. When viewed in a planar fashion as in Fig. 2, the linear portions **412** may, in some embodiments, form an angle Ω , relative to the cylindrical

axis of the stent. In some embodiments, Ω may be approximately equal to the helical angle of the first helical segments **30** and **40**. In one embodiment, the second circumferential elements **60** may have an amplitude **300** (see Figs. 3, 4, and 6) ranging from 0.5 mm to 2.0 mm and a period ranging from 0.5 mm to 2.0 mm. Other ranges may be used depending on the particular stent size and design being employed. In one embodiment, the preferred period is about 0.82 mm and the preferred length of the linear portion **412** is about 0.5 mm and the amplitude **300** is about 0.38 mm. The amplitude of the second circumferential element **60** may be greater than, equal to, or less than the amplitude of the first circumferential element **50**. In one embodiment, the circumferential contributions of the first circumferential elements **50** to the overall circumference of the main body **11** is greater than the circumferential contribution of the second circumferential element **60**, in terms of either circumferential length or circumferential cylindrical surface area. In one embodiment, the stent may have an overall outer surface area of about 0.029 square inches.

As is shown in Figure 7, the stent may have a main body **11** comprised of two or more first helical segments **30** and **40**, as well as two or more second helical segments **200** and **210**. The first and second helical segments **30**, **40** and **200**, **210**, respectively, are joined together to form a generally cylindrically shaped body **11**. In some, but not all embodiments, the first and second helical segments may share a common connecting element **250**. In some embodiments, the common connecting element **250** may be H-shaped and the two generally parallel linear portions of the H-shaped connecting segment **250** may form an angle δ relative to the axis **5**. (See Fig. 6). δ may, in one embodiment, be about 14 degrees. As is shown in Figure 7, the first helical segments **30** and **40** and second helical segments **200** and **210** may have different pitches, i.e. number of spirals per unit length, which results in the first and second helical segments as having different helical angles (θ and β , respectively) i.e. the angle of the helical segment relative to the cylindrical axis **5** of the stent. In one embodiment, the second helical segments **200** and **210** have a pitch approximately twice that of the first helical segments. In one embodiment θ may vary from 0 to 45 degrees and is preferably about 40 degrees and β is preferably about twice θ . In other embodiments the angle θ may range from 0 to 90 degrees to the circumference **110** of each cylindrical element **100**.

As is shown in Figures 2, 3, 4, and 6, the helical segments **30**, **40** are circumferentially expandable (i.e. they expand along the circumference of the stent) and may be formed from a plurality of circumferential elements **60** that in turn are made up of linear **412** and/or curved **414** segments (see Fig. 6) that each have a filament width **407** (see Fig. 6) that is less than the circumferential dimension **66** of the circumferential element **60** (see Fig. 3). In some embodiments, each helical segment **30** or **40** will make a total contribution to the circumference

of each cylindrical element 100 that is greater than the filament width 407. The circumferential contribution of each helical segment 30 or 40 to the overall circumference of the stent (110 in Figure 1 or 105 in Figure 11) may be greater than the circumferential contribution of the filament widths 407 of the segments (e.g. 412 and 414) making up the circumferential elements 60 that in turn make up the helical segments. (I.e., In some embodiments the circumferential contribution of the helical segments 30 and 40 to the circumference 110 of each cylindrical element 100 is more than just a function of the filament width 407, e.g., it may be a function of the geometry of the element 60.) For the embodiment shown in Figures 1 and 11, this is the case when the stent is in both the unexpanded and expanded state. The geometry of the helical segments 30 and 40 are a factor in determining their expandability.

Likewise, the helical segments 200, 210 are circumferentially expandable and may be comprised of other circumferential elements 50 that are in turn comprised of linear 320 and/or curved segments 328 (see Figs. 3 and 5) that have a filament width 420 (see Fig. 4). The contribution of the helical segments 200, 210 to the overall circumferential dimension 110 of each cylindrical element 100 is greater than just the contribution of the filament widths 420 of the individual segments 320 and 328 that make up the elements 50 that in turn make up the helical segments 200, 210. The geometry of the elements 50 making up the helical segments 200, 210 may be a more important factor in determining the circumferential contribution of the helical segments 200 and 210 to the overall stent circumference than the filament width 420. Thus, in one embodiment of the present invention, the circumference of the stent 110 in its unexpanded state and the circumference 105 when the stent is expanded are primarily functions of the geometry of the elements 50 and 60 that make up the helical segments 30, 40 and 200, 210, respectively.

Some, but not all embodiments, of the present invention may employ endzones 10 and 20. (See Figs. 1, 2, and 11). Stents that employ endzones will generally have two endzone regions straddling a central zone in the middle of the stent. The stents may also have a transition region between the endzone and the central zone. The transition region serves to help smoothly transition between the expanded middle region and an portions of the end of the stent that remain unexpanded after the stent is implanted. The size and characteristics of the transition region are a function of the material and geometry of the stent. For example, the transition range properties vary as a function of, among other things, the helical angle of the first helical segments, the number of curved segments located in the endzones, and the angle ϵ of the linear portions of the segments forming the endzones. (See e.g. Fig. 8).

The endzones 10 and 20 may take numerous forms. In some embodiments, the endzones may be comprised of one or more rings 17. (See Fig. 8). The rings 17 may be generally

cylindrically shaped, and in some embodiments, right cylindrically shaped. In one embodiment, the rings are formed from linear segments 28 joined together by curved segments 29 to form a pattern. The pattern, which is preferably – but not necessarily – a repeating pattern may take numerous forms, including the one shown. The endzones 10 and 20 may be comprised of a plurality of rings 17 attached together. Struts 15 may be used to attach the rings together to form the endzone and to attach the endzone to the main body 11. The struts, in some embodiments, act as cantilever springs and their stiffness, which is a function of their width and thickness, may define bending properties of the stent along its cylindrical axis 5.

In the embodiment shown in Figs. 1, 7, 8, and 9, which is exemplary only, the linear segments 28 in the endzone 10, are oriented at an angle ϵ relative to the cylindrical axis of the stent. The angle ϵ may range from 0 to 45 degrees and in one embodiment is preferably about 10 degrees. The segments of the endzone may have a filament width 13 of between 0.002 and 0.007 inches. In one embodiment, the repeating pattern of the endzone has a period 2 of about 0.027 inches and an amplitude 21 of about 0.043 inches. Other values may be used. As is shown in Figure 1, the struts 15, which are but one way to attach the endzones 10 and 20 to the main body 11, may, in one embodiment have a width of between 0.002 inches and 0.08 inches and preferably the width does not exceed the wall thickness, which typically --but not necessarily ranges from about 0.002 to 0.008 inches.

The stent of the present invention may, after insertion into a vessel, be expanded such that it plastically deforms from the unexpanded state to an expanded state having a diameter increase of about 400 to 500%, which results in a larger circumference 105. (See Figure 11). Figure 11 depicts the stent shown in Figure 1 in an expanded state. Upon expansion the stent's outer diameter in one particular embodiment increases from 1.0 mm to 3.00 mm and maintains a stent-to-vessel ratio in the expanded state that is greater than on average 16%.

While endzones 10 and 20 may be used to provide square edge, not all stents according to the present invention require endzones. Figures 12-15 depict an endzoneless stent. Like the stent shown in Figures 1-9, the stent of Figures 12-15, comprises a plurality of adjacent cylindrical elements 100. The cylindrical elements 100 are formed from a plurality of first circumferential elements 50' and second circumferential elements 60. The first circumferential elements 50' of the stent in Figures 12-15 are substantially identical to the second circumferential element 60 except that they are rotated to have a different orientation. The circumferential elements may be generally S-shaped having a linear portion 412, a curved portion 414 having a radius R , and an angled portion 417. R may vary widely depending on overall stent characteristics and in one embodiment varies between 0.001 and 0.02 inches and is preferably about 0.0083 inches. The angled portion 417 is spaced a distance 499 from the linear

portion. In one particular embodiment, the distance 499 may vary from 0.002 to 0.020 inches and is preferably about 0.007 inches. The filament width 407 of the elements may, in one embodiment, be about 0.13 mm.

Adjacent cylindrical elements 100 are joined together by connecting first circumferential elements 50' in each cylindrical element 100 with first circumferential elements 50' in an adjacent cylindrical element 100, such that the first circumferential elements 50' in adjacent cylindrical elements 100 form helixes through the stent and such that second circumferential elements form helixes through the stent having an angle θ relative to the axis 5. In some embodiments, a connecting segment 250 (see Fig. 7) is used to connect first circumferential elements in adjacent cylindrical elements 100 and to connect second circumferential elements 60 in adjacent cylindrical elements 100. In addition, the connecting segment, connects first circumferential elements 50' in each cylindrical element 100 with two second circumferential elements 60 in each cylindrical element 100. In one embodiment, the individual cylindrical elements 100 are adjacent to each other and are located a distance 666 apart. In one embodiment, the preferred may range between 0.002 and 0.020 inches, and is preferably about 0.009 inches.

The above description of the stent of the present invention is illustrative and not exhaustive. Various modifications may be made to the stent to change its overall characteristics without deviating from the scope and spirit of the invention as defined by the claims. For example and without limitation, the increasing the length of the linear segments and or increasing the arc of the second circumferential elements 60 will decrease the amount of radial force required to expand each circular section and will increase flexibility. Increasing the angle Ω of the second circumferential element 60 will: (i) increase the amount of radial force required for expansion, (ii) increase surface area, and (iii) decrease flexibility. Likewise, various modifications may be made to the struts 15. (See Fig.2). Increasing strut width and wall thickness will: (i) increase surface area, (ii) increase radial strength, (iii) increase pressure required to expand the stent radially, (iv) decrease flexibility, and, in the case of increased wall thickness, (v) increase radiopacity.

The stent of the present invention may be manufactured in numerous ways. The stent may be formed from a metallic tube by removing various portions of the tube's wall to form the patterns described herein. The resulting stent will thus be formed from a single contiguous piece of material, eliminating the need for connecting various segments together. Material from the tube wall may be removed using various techniques including laser (YAG laser for example), electrical discharge, chemical etching, metal cutting, a combination of these techniques, or other well known techniques. See e.g. U.S Patent Nos. 5,879,381 to Moriuchi et al. and 6,117,165 to

Becker, which are hereby incorporated in their entirety by reference. Forming stents in this manner allows for creation of a substantially stress-free structure where the helical segments are integral with the circumferential elements. In one embodiment, the tube from which the stent is formed may have an internal diameter of about 3.0 mm, a wall thickness of about 1.0 mm and a length of about 30 mm. Tubes having other dimensions may be used. In particular, the length may be adapted to that of the diseased part of the lumen in which the stent is to be placed. This may avoid using separate stents to cover the total diseased area.

Those skilled in the art will recognize that the stent and manufacturing method described above are illustrative and not exhaustive of the present invention and that modifications and variations may be made without deviating from the scope and spirit of the invention as defined by the following claims.